



KV-TF40

PID Temperature Adjustment Unit (Multi-input 4-channel)



*Please note that accessories depicted in the image are for illustrative purposes only and may not be included with the product.

Specifications

Model	KV-TF40	
Type	Temperature control unit	
Memory elements	EEPROM rewritable one million times	
Number of temperature input points	4 ch	
Input	Thermocoupler/Platinum temperature measuring resistor*1	
Temperature sensor types	Thermocoupler: K, J, T, E, R, B, N, S, W5Re/W26Re Platinum temperature measuring resistor: JPt100, Pt100	
Indicated accuracy	±0.3% of F.S. ±1 digit (at 25°C 77°F), ±0.7% of F.S. ±1 digit (at 0 to 50°C 32 to 122°F)	
Cold junction correction precision	±1°C ±1.8°F	
Sampling cycle	125 ms/ch (500 ms/4 ch)	
Control period	1 to 100 seconds	
Operation mode	PID control (with auto-tuning and 3 mode stabilizer function installed), Heat/cool PID control (with auto-tuning and 3 mode stabilizer function installed), ON/OFF control	
Tuning mode	PID auto-tuning mode	
Control output	Transistor (sink)	
Alarm output	Transistor (sink)*2	
Alarm mode	Absolute value upper limit, absolute value lower limit, deviation upper limit, deviation lower limit, deviation upper limit unexcited, deviation lower limit unexcited, deviation upper and lower limits, within upper and lower limit deviation, absolute value upper limit unexcited, absolute value lower limit unexcited*3	
Output	Rated load	30 VDC, 100 mA or less
	Leakage current at OFF	100 µA or less
	Residual voltage at ON	1.5 V or less
Current sensor (CT) input	4 ch*4	
Current measurement precision	Larger of ±5% of an input value and ±2 A of an input value	
Insulation mode	Between inputs and outputs: Photocoupler and transformer insulation, Between input channels: Photocoupler and transformer insulation	
Others	Heater wire breaking alarm, control loop wire breaking alarm, measured value bias, output limit, slope setup, manual reset, output control when an error occurs	
Internal current consumption	210 mA or less	
Weight	Approx. 270 g	

*1 Can be set for each channel.

*2 Because the alarm output is used as cooling control output when heat/cool control is used, the alarm output cannot be used as an alarm output function.

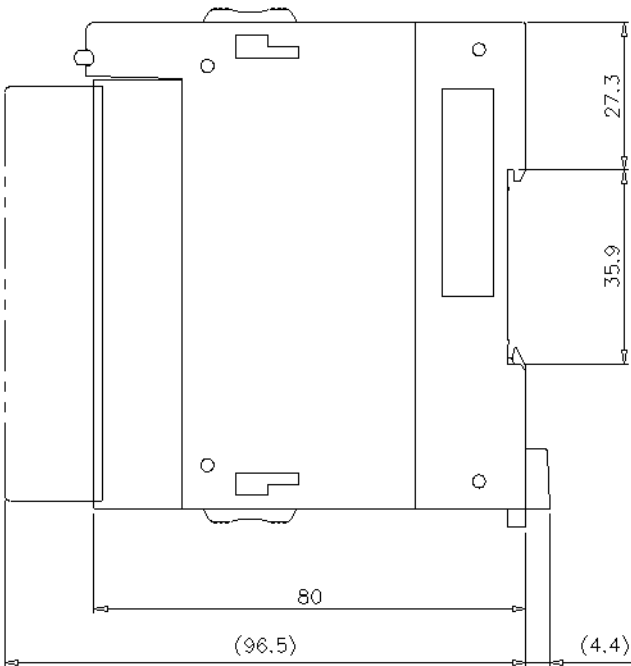
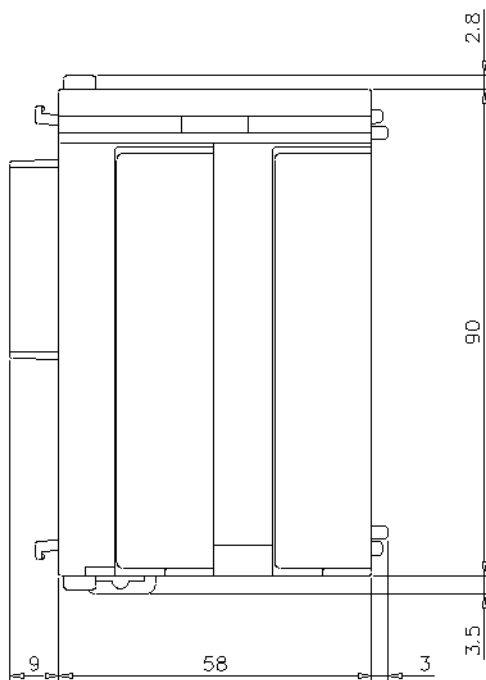
*3 Standby operation ON/OFF can be selected in each alarm mode.

*4 Use a KEYENCE sensor (OP-6694). (Sold separately.)

Dimensions

* Download CAD file or product manual for larger image/text and more detail.

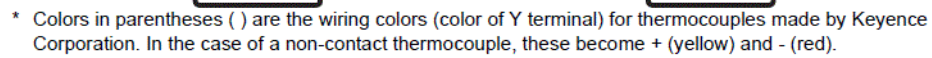
KV-TF40



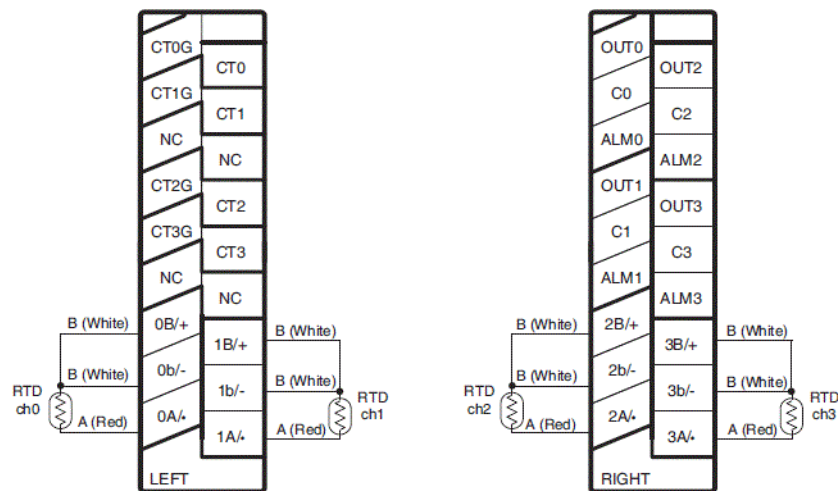
* Download CAD file or product manual for larger image/text and more detail.

Refer to the following wiring diagram when wiring the I/O terminal.

Thermocouple wiring

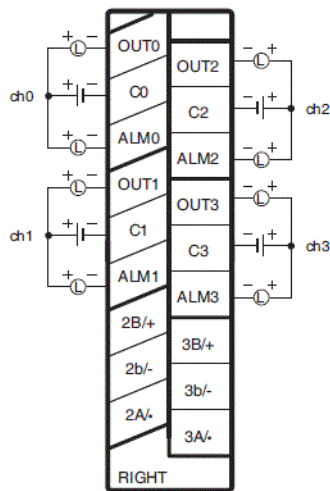


RTD wiring

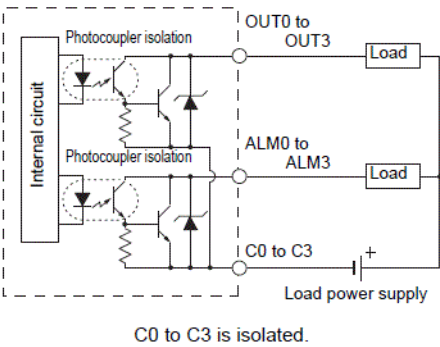


* Colors in parentheses () are the wiring colors (color of Y terminal) for RTDs made by Keyence Corporation.

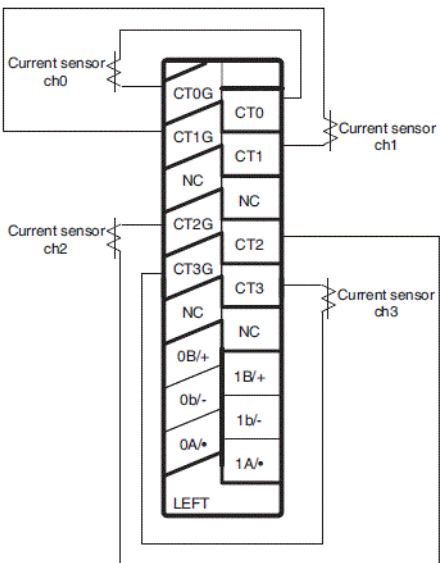
■ Control output and alarm output wiring



■ Output circuit diagram



■ Current sensor (OP-6694) wiring



NOTE

- The current sensor (OP-6694) does not have polarity.
- All current sensor input GNDs (CT0G to CT3G) are short-circuited internally.